



## *Zero Bin test (or trigger delay)*

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INOE, Romania

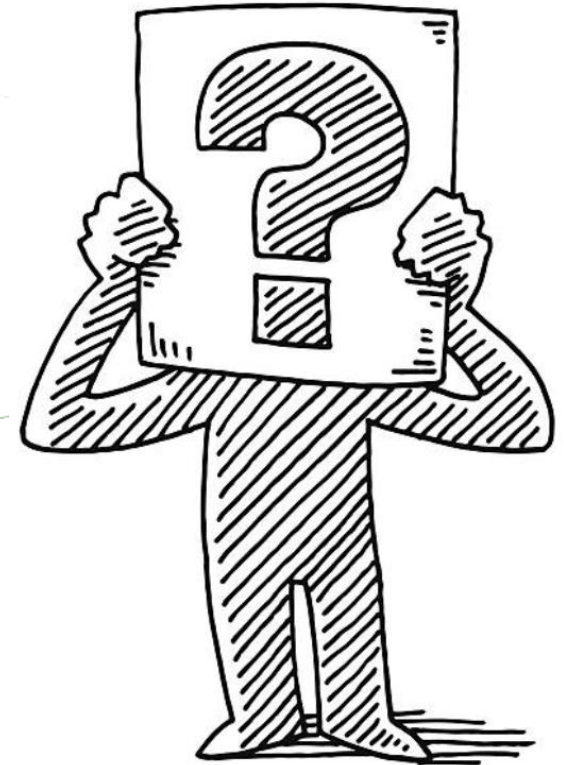
**IR0000032 – ITINERIS, Italian Integrated Environmental Research Infrastructures System**  
(D.D. n. 130/2022 - CUP B53C22002150006) Funded by EU - Next Generation EU PNRR-  
Mission 4 “Education and Research” - Component 2: “From research to business” - Investment  
3.1: “Fund for the realisation of an integrated system of research and innovation infrastructures”



# What is the Zero Bin Test?

A **diagnostic procedure** used to verify the **timing alignment between:**

1. the **actual laser pulse emission**  
**and**
2. the **recorded zero-bin position** (which represents the start of the return signal).

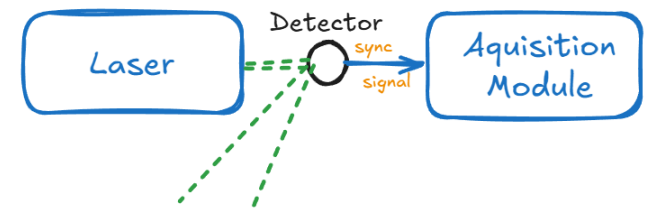
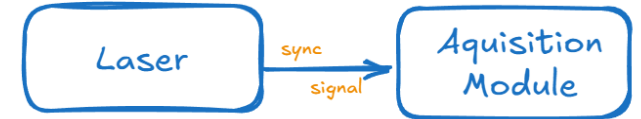
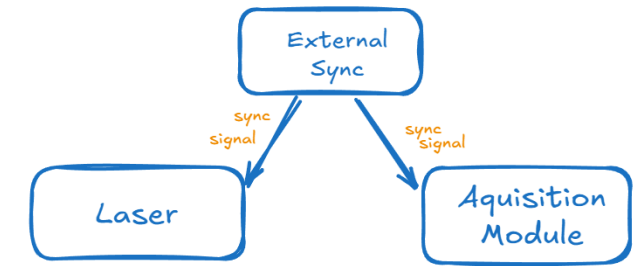


# Why Do We Need the Zero Bin Test?

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## We know that:

- In lidar systems, the acquisition of backscattered signals must be **accurately synchronized** with the **moment of laser emission**.
- This synchronization is typically achieved in several ways:
  - a) **Using an external synchronization module**, which sends a common trigger to both the laser and the acquisition system (with a predefined delay given by the user).
  - b) **Using the laser's own internal sync signal**, typically the **Q-switch output**, as the master trigger.
  - c) **Using an optical sensor** placed in the laser beam path, which generates a signal **when the laser pulse is physically emitted** (i.e., it detects the actual light).

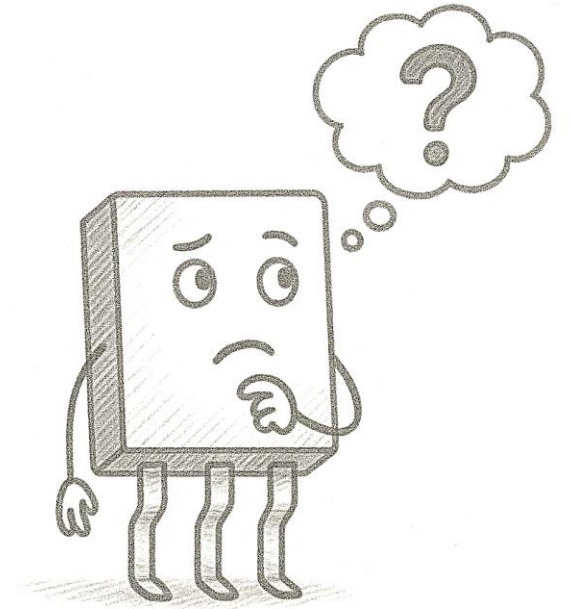


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## As a consequence:

The trigger signal is **processed by independent electronic units** (e.g., in the laser and in the acquisition system), which often have:

- a) **Different internal processing delays,**
- b) **Varying reaction times** depending on design



## Why Do We Need the Zero Bin Test?

This can result in a **delay between the actual moment the laser light is emitted and the start of data acquisition**, causing a systematic **time offset** in the recorded signal.

# Why Do We Need the Zero Bin Test?

## We also know (for licel based modules)

- The **analog** and the **photon counting** data **has a fixed shift between them.**
- This is a result of two factors:
  - a) Analog preamplifier contains an antialias filter which has a bandpass of half the sampling frequency » delays the analog by 2 bins
  - b) ADCs sample the voltage in a multiple step process » the sample result will be available several clock cycles later

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**Delay between analog and photon counting (Bin shift)**

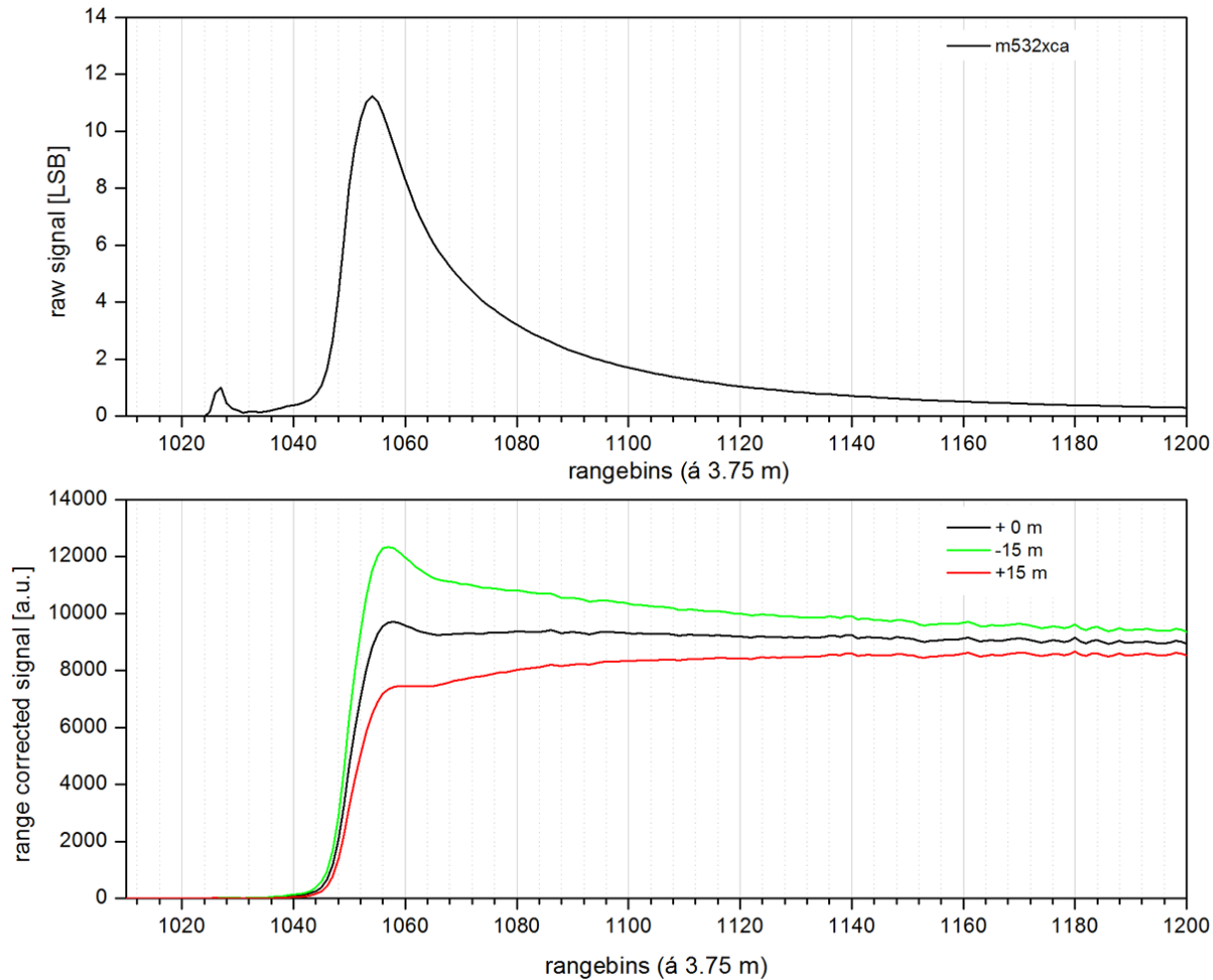
## Why Do We Need the Zero Bin Test?

We need to **synchronize the time axis** of the lidar signal with the actual atmospheric return.

## What happens if we do not synchronize?

All lidar products will have a range dependent offset, especially in the lower altitudes.

# Why Do We Need the Zero Bin Test?

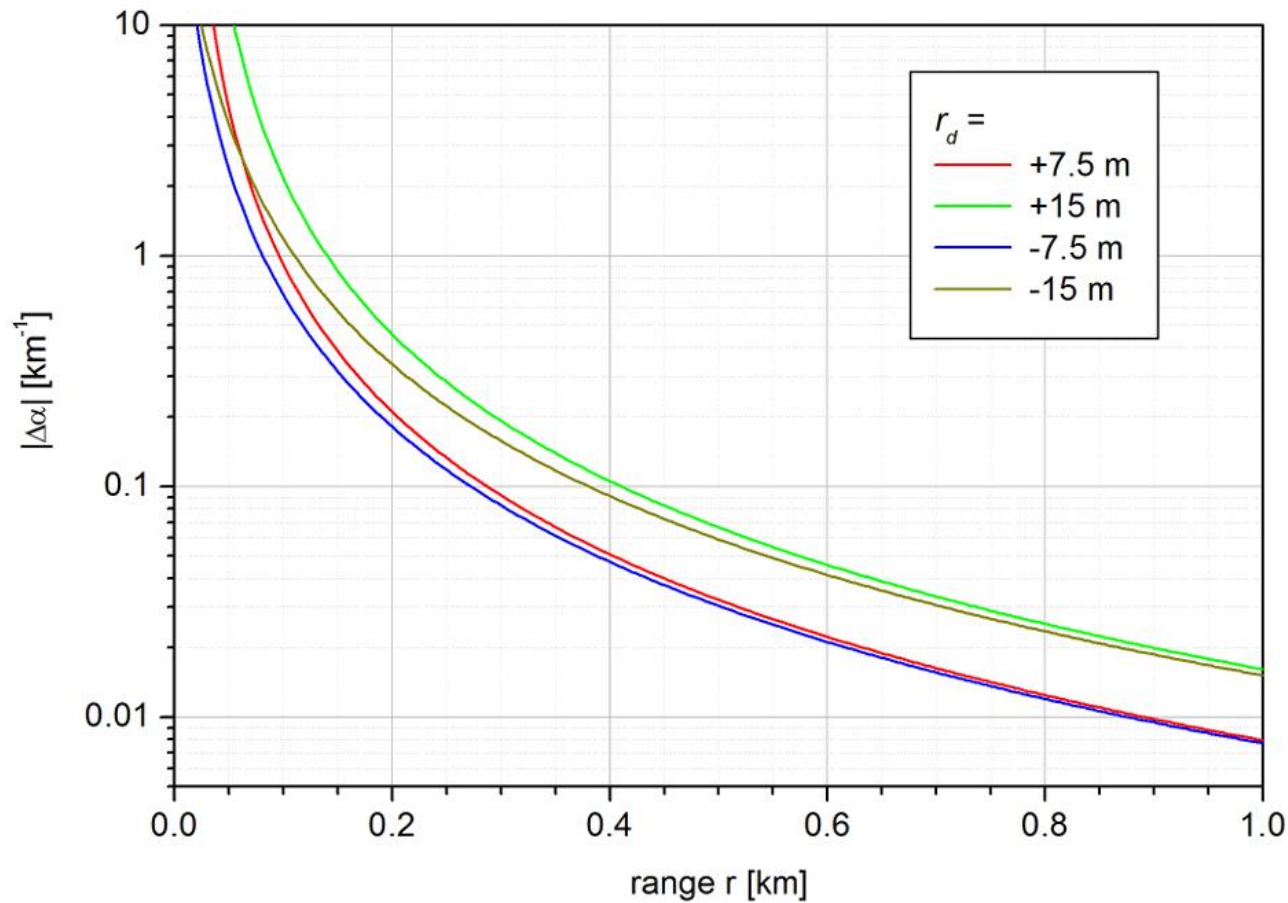


*Freudenthaler, V., et al., 2018*

Raw analogue lidar signal  
with 1026 rangebins  
pretrigger

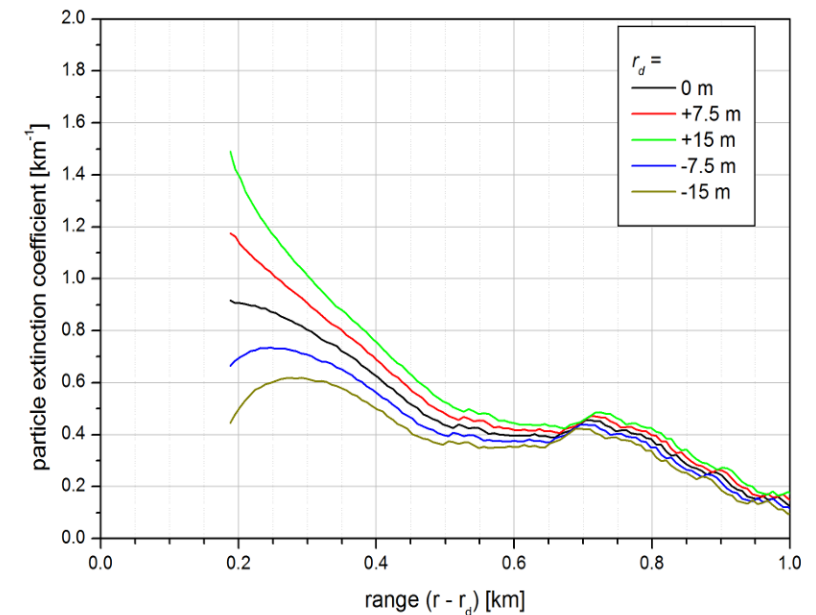
Range corrected signal of  
the top panel with three  
different laser trigger  
delays

# Why Do We Need the Zero Bin Test?



Freudenthaler, V., et al., 2018

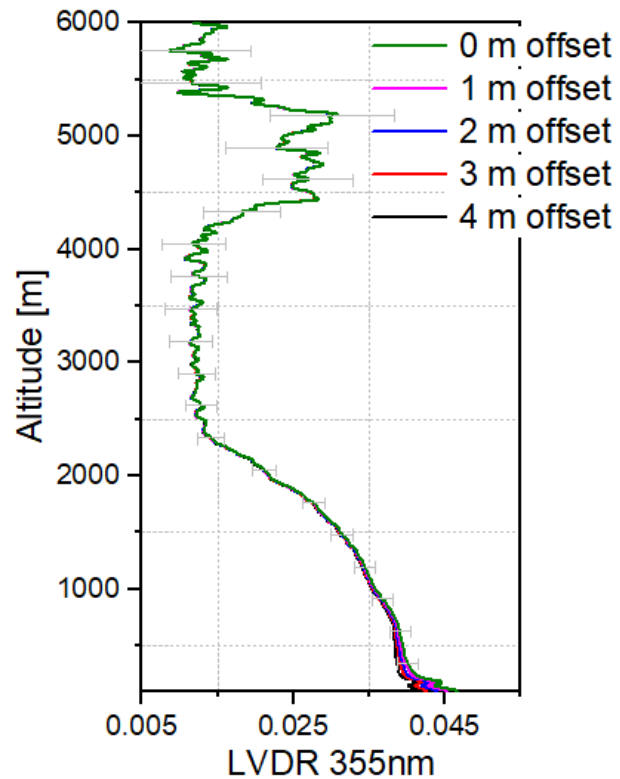
Absolute error of the extinction coefficient from Raman measurements @355/387 nm due to uncertainties of the zero bin



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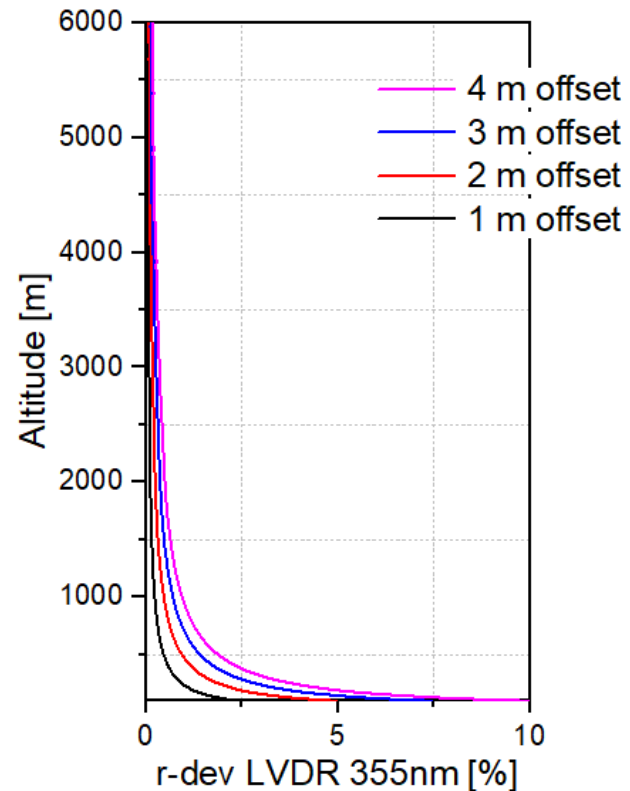
### Linear Volume Depolarization Ratio

- offset between the two depolarization components



### Relative Deviation LVDR

- offset between the two depolarization components



*Belegante, L., et al., 2022, ILRC*

Bias in the linear volume depolarization ratio (VLDR), which is sensitive to trigger offsets affecting one polarization channel.

# Concluding.....

## Common Issues Without Zero Bin Calibration

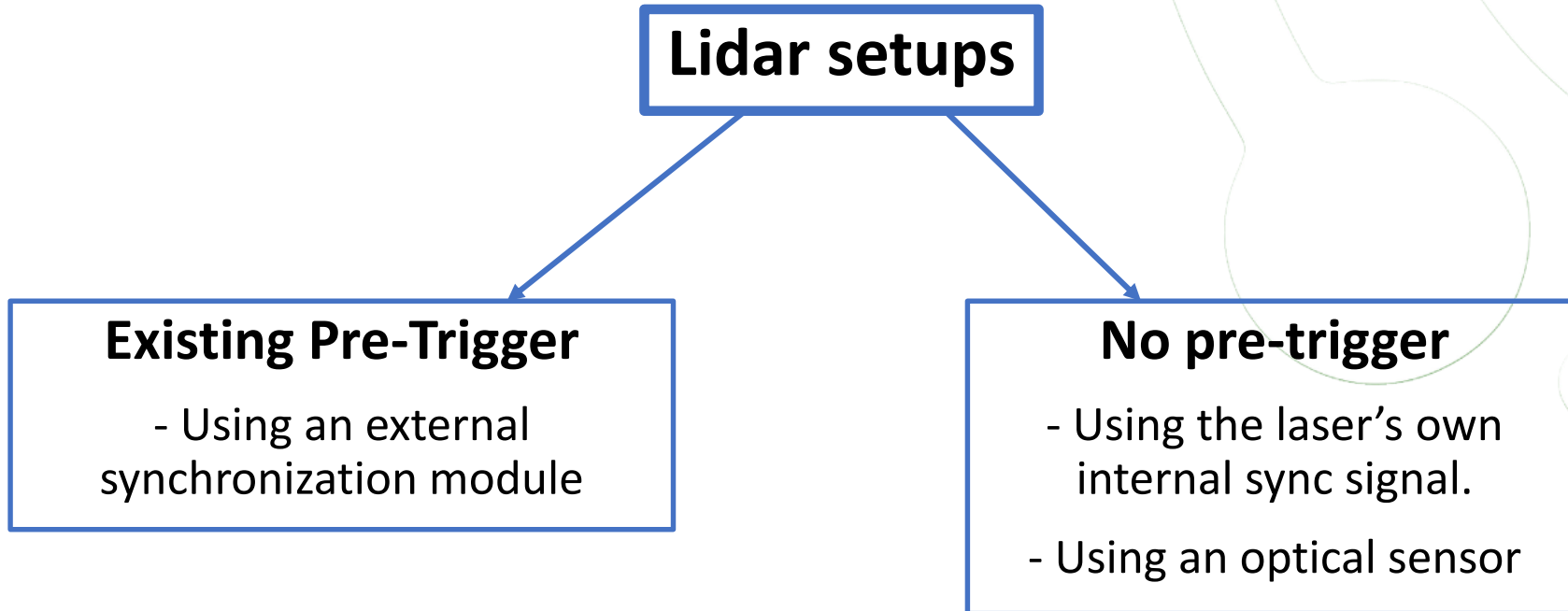
- **Incorrect altitude assignment** of aerosol/cloud layers.
- **Biases** in backscatter and polarization retrievals with severe distortions in Raman retrievals due to signal slope changes in the near range (~1 km).
- **Misalignment with other lidar datasets** during inter-comparisons.
- **Mismatches** between lidar-derived atmospheric profiles and **radiosonde data**, leading to errors in temperature, pressure, and extinction coefficient retrievals during inversion.

# How Do We Assess the Zero Bin?

*Experimental Methods for Detecting the Zero Bin*

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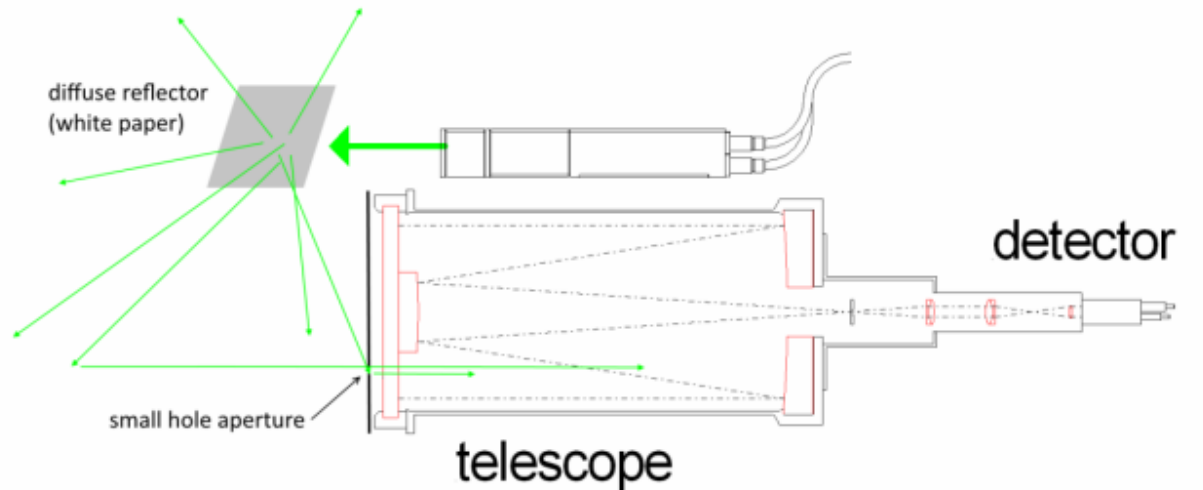
*Experimental Methods for Detecting the Zero Bin*

## Existing Pre-Trigger

**Stray light reflections from lab walls or exit window** can provide a peak in the recorded signal, allowing zero-bin identification.

A **diffuse scattering target** blocking the laser path can be used.

In both cases - **Telescope must be almost fully covered, leaving a small section of the telescope opened.**



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## Existing Pre-Trigger

**Tip:** the open section of the telescope should be chosen close to the laser emission - in the N sector for large telescopes (300-400 mm diameter).

**Tip:** Look at the live preview of the signals and adjust how large the open section needs to be (25-50% of the detection scale).

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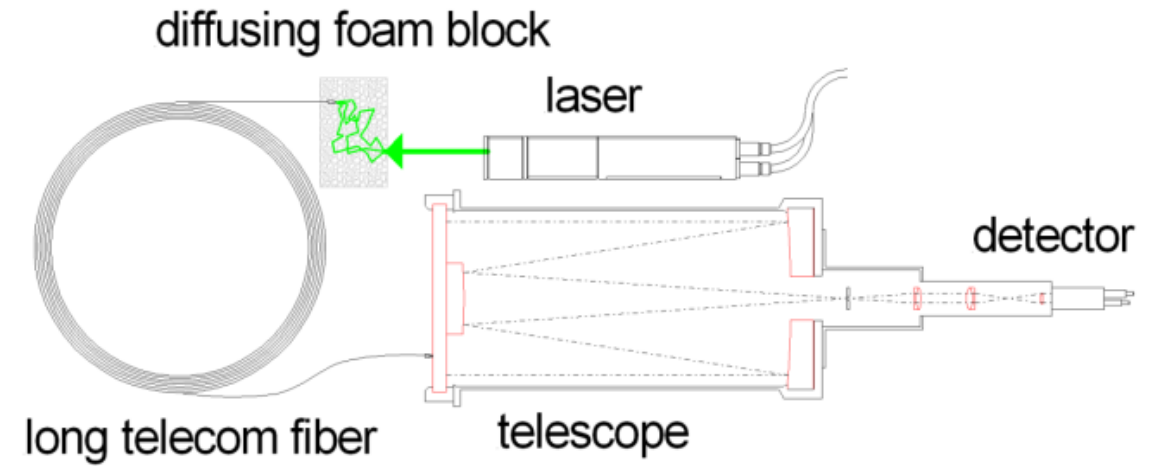
## No Pre-Trigger

A near-range **target** at a known distance from the lidar can provide a calibration reference.

A **fiber-optic delay** method can be used: The laser pulse is attenuated and fed into an optical fiber of length  $s$ .

The fiber output is positioned in the telescope volume to generate a delayed reference pulse. The telescope must be covered.

**Open-cell foam** and cheap communication fibers are useful for this technique.



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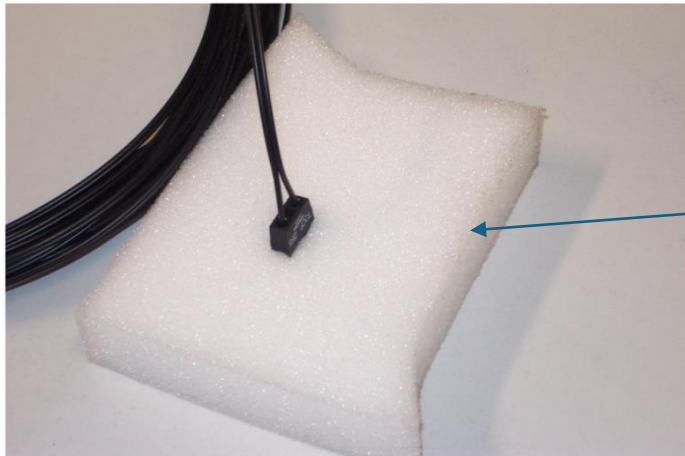
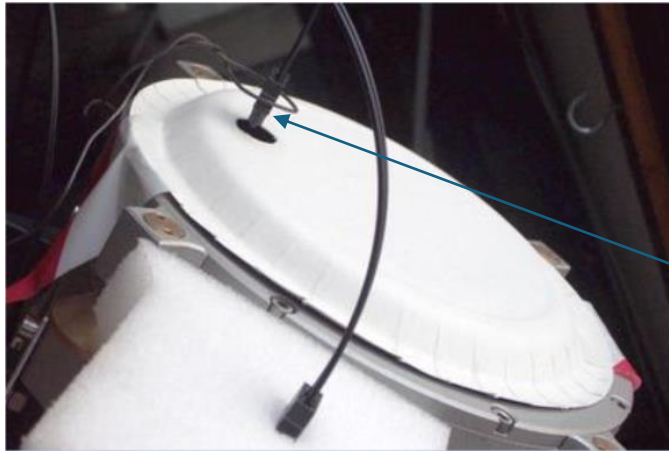
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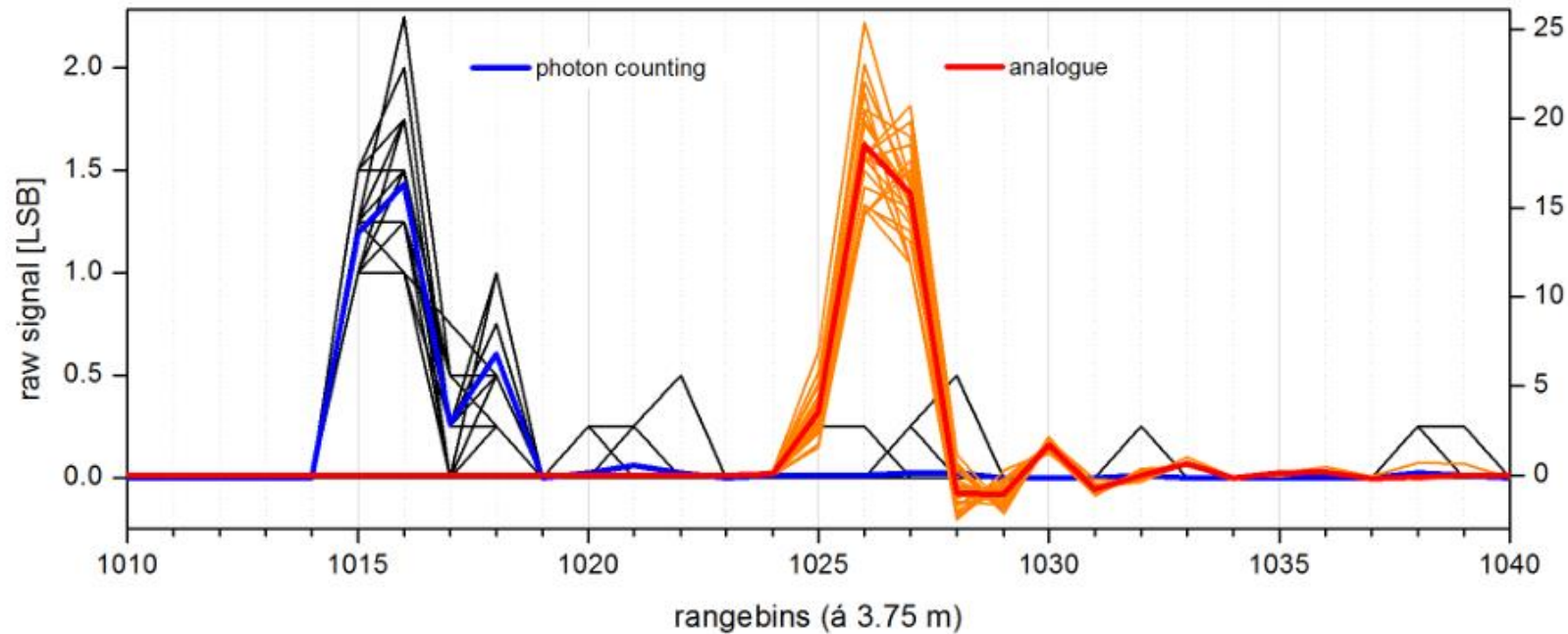
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## Data visualization

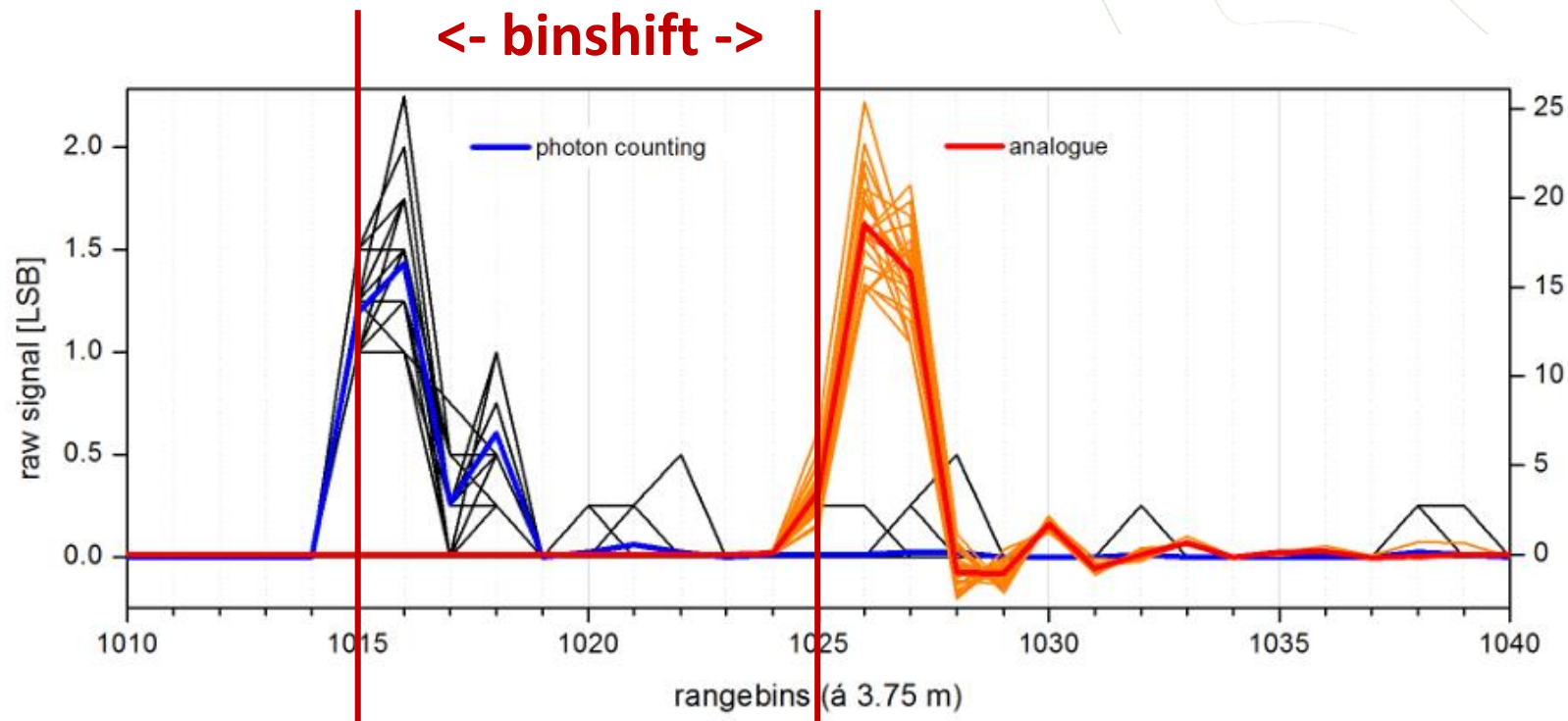


*Freudenthaler, V., et al., 2018*

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## Data visualization



*Freudenthaler, V., et al., 2018*



# THANKS!

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